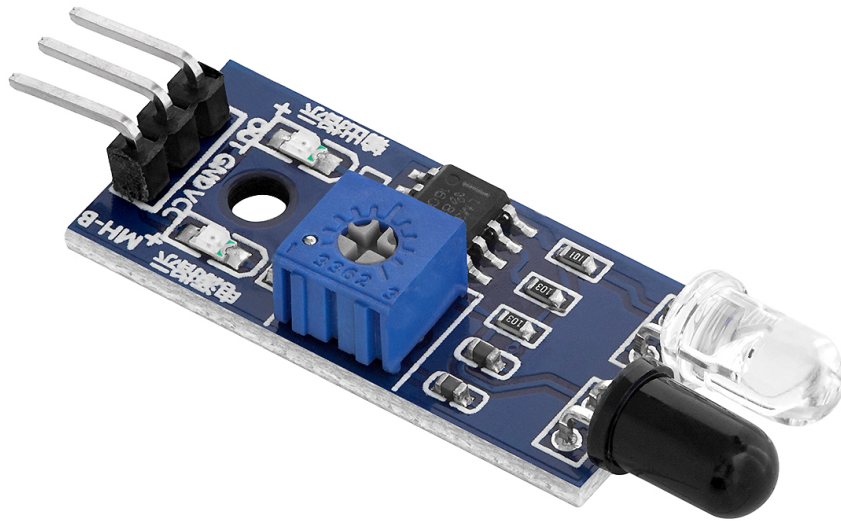


AZ-Delivery

Welcome!

Thank you for purchasing our *AZ-Delivery Obstacle Detection Sensor Module*. On the following pages, you will be introduced to how to use and set-up this handy device.

Have fun!



Az-Delivery

Table of Contents

Introduction.....	3
Specifications.....	4
The pinout.....	5
How to set-up Arduino IDE.....	6
How to set-up the Raspberry Pi and Python.....	10
Connecting the module with Uno.....	11
Sketch example.....	12
Connecting the module with Raspberry Pi.....	14
Libraries and tools for Python.....	15
Python script.....	16

Az-Delivery

Introduction

The obstacle detection sensor module is a device that is used to detect obstacles. It is a multipurpose device and can be used in many applications for detecting objects, collision detection, edge avoidance, color detection, fire detection, line sensing and as an encoder for counting objects. The module can be a part of other devices such as robots, machines, security systems, etc.

The obstacle detection sensor is a device that emits and detects infrared light in order to sense the changes that occur in surroundings. It detects light in the wavelengths between 0.75 to $1000\mu m$.

The module consists of a LED (Light emitting diode) as a transmitter, a photodiode as a receiver and an operational amplifier which acts as a voltage comparator. It measures the voltage threshold of the photodiode in series with a resistor. When the voltage drops below, the threshold output of the operational amplifier will be HIGH and the signaling LED will turn ON, which indicates that the object is detected.

The output signal is digital and the output pin can be in two states as HIGH or LOW. When the output pin is in the HIGH state the voltage will be at maximum and when it is in a LOW state, the voltage will be at $0V$.

Az-Delivery

Specifications

Operating voltage	from 3.3V to 5V
Operating current	20mA
Detection range	20mm to 200mm
Detection angle range	35° degree
Output signal	Digital
Mounting hole diameter	3mm
Dimensions	48x14x7mm (1.9x0.5x0.3in)

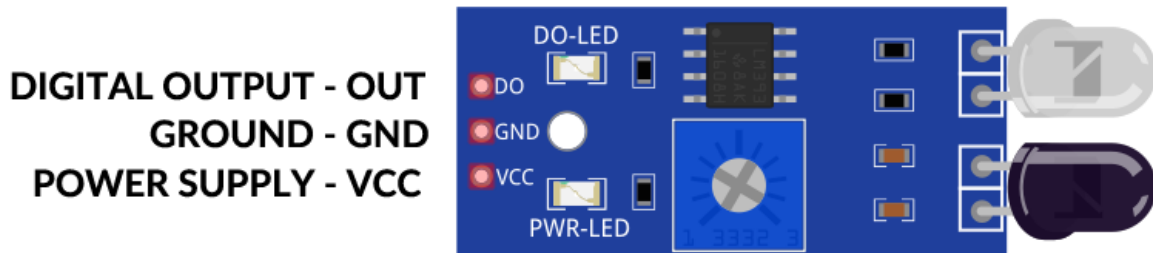
The module has on-board LEDs which are used for power and detection indication.

The module sensitivity can be adjusted with an on-board potentiometer. Moving the potentiometer shaft into the clockwise direction increases sensitivity. Moving the shaft of the potentiometer in the counterclockwise direction decreases the sensitivity of the module.

Az-Delivery

The pinout

The obstacle detection sensor module has three pins. The pinout is shown on the following image:



The module operates in both the 3.3V and 5V voltage ranges.

NOTE: When using the module with the Raspberry Pi, connect the VCC pin of the module to the 3.3V. Connecting this pin to the 5V could damage the Raspberry Pi.

Az-Delivery

How to set-up Arduino IDE

If the Arduino IDE is not installed, follow the [link](#) and download the installation file for the operating system of choice.

Download the Arduino IDE



The screenshot shows the Arduino IDE download page. On the left, there is a teal circular logo with a white infinity symbol containing a minus and a plus sign. To the right of the logo, the text reads: **ARDUINO 1.8.9**. Below this, it states: "The open-source Arduino Software (IDE) makes it easy to write code and upload it to the board. It runs on Windows, Mac OS X, and Linux. The environment is written in Java and based on Processing and other open-source software. This software can be used with any Arduino board. Refer to the [Getting Started](#) page for Installation instructions." On the right side of the page, there are several download options: "Windows Installer, for Windows XP and up" and "Windows ZIP file for non admin install"; "Windows app Requires Win 8.1 or 10" with a "Get" button; "Mac OS X 10.8 Mountain Lion or newer"; "Linux 32 bits"; "Linux 64 bits"; "Linux ARM 32 bits"; and "Linux ARM 64 bits". At the bottom right, there are links for "Release Notes", "Source Code", and "Checksums (sha512)".

For *windows* users, double click on the downloaded .exe file and follow the instructions in the installation window.

Az-Delivery

For *Linux* users, download a file with the extension `.tar.xz`, which has to be extracted. When it is extracted, go to the extracted directory and open the terminal in that directory. Two `.sh` scripts have to be executed, the first called `arduino-linux-setup.sh` and the second called `install.sh`.

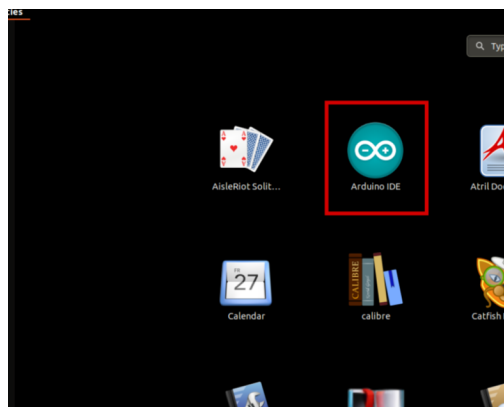
To run the first script in the terminal, open the terminal in the extracted directory and run the following command:

```
sh arduino-linux-setup.sh user_name
```

user_name - is the name of a superuser in the Linux operating system. A password for the superuser has to be entered when the command is started. Wait for a few minutes for the script to complete everything.

The second script, called `install.sh`, has to be used after the installation of the first script. Run the following command in the terminal (extracted directory): **sh install.sh**

After the installation of these scripts, go to the *All Apps*, where the *Arduino IDE* is installed.



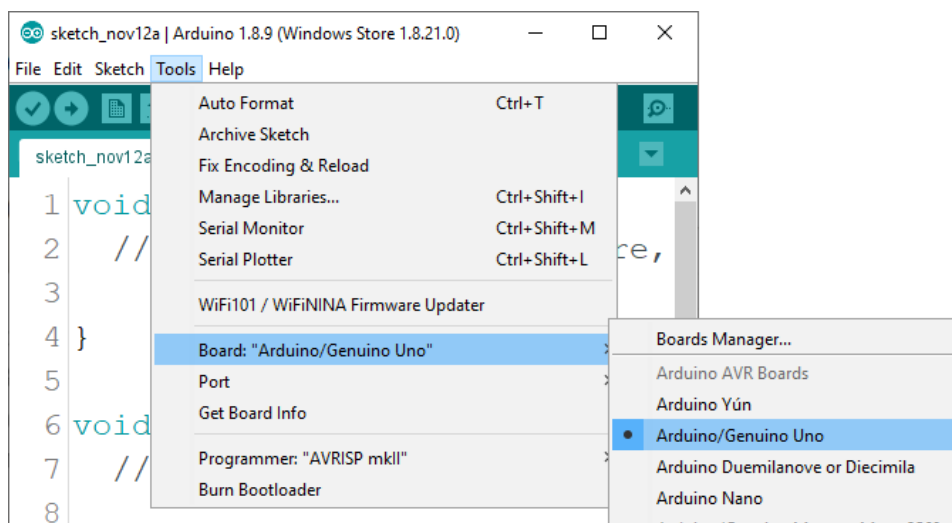
Az-Delivery

Almost all operating systems come with a text editor preinstalled (for example, *Windows* comes with *Notepad*, *Linux Ubuntu* comes with *Gedit*, *Linux Raspbian* comes with *Leafpad*, etc.). All of these text editors are perfectly fine for the purpose of the eBook.

Next thing is to check if your PC can detect an Arduino board. Open freshly installed Arduino IDE, and go to:

Tools > Board > {your board name here}

{your board name here} should be the *Arduino/Genuino Uno*, as it can be seen on the following image:

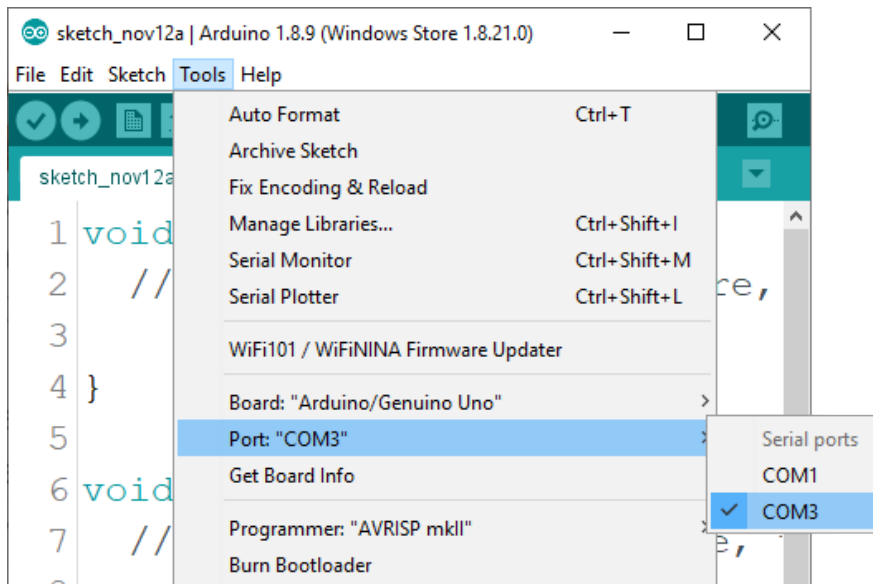


The port to which the Arduino board is connected has to be selected. Go to:
Tools > Port > {port name goes here}

and when the Arduino board is connected to the USB port, the port name can be seen in the drop-down menu on the previous image.

Az-Delivery

If the Arduino IDE is used on Windows, port names are as follows:



For *Linux* users, for example port name is `/dev/ttyUSBx`, where *x* represents integer number between 0 and 9.



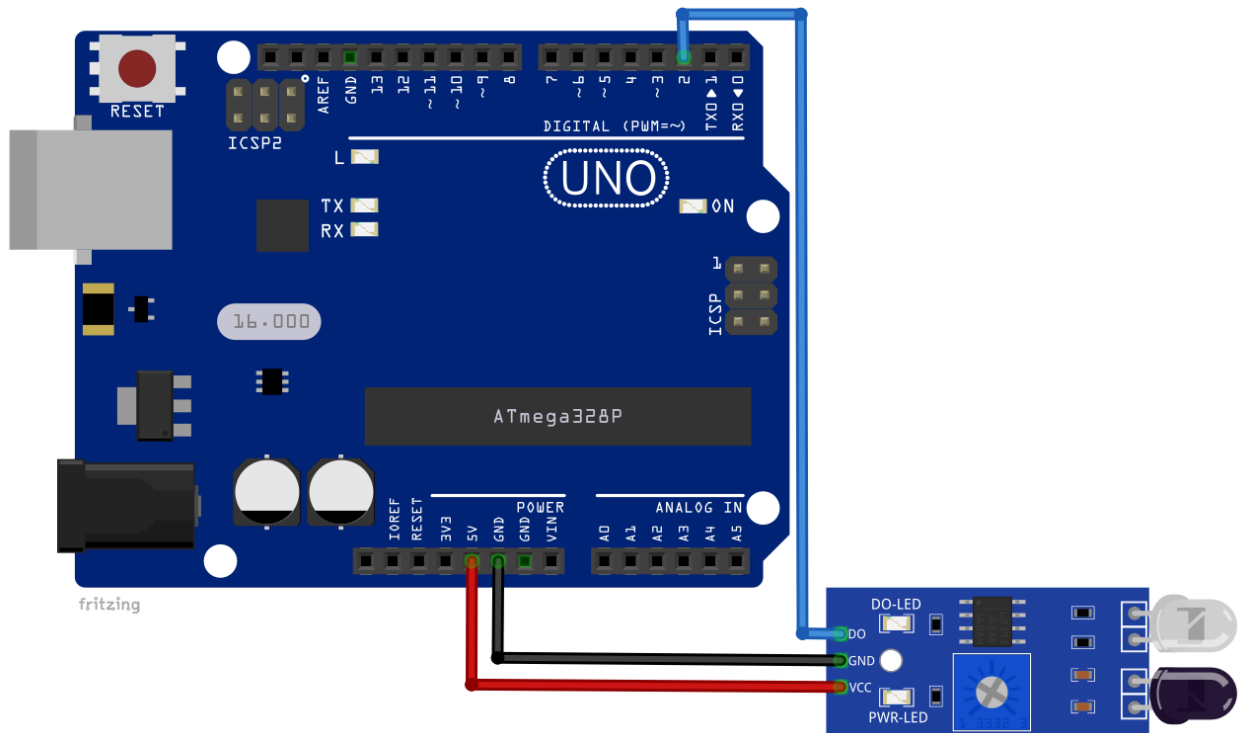
How to set-up the Raspberry Pi and Python

For the Raspberry Pi, first the operating system has to be installed, then everything has to be set-up so that it can be used in the *Headless* mode. The *Headless* mode enables remote connection to the Raspberry Pi, without the need for a *PC* screen Monitor, mouse or keyboard. The only things that are used in this mode are the Raspberry Pi itself, power supply and internet connection. All of this is explained minutely in the free eBook: [Raspberry Pi Quick Startup Guide](#)

The *Raspbian* operating system comes with *Python* preinstalled.

Connecting the module with Uno

The module has three pins. The pinout is shown on the following image:



Module pin	Uno pin	Wire color
OUT	D2	Blue wire
GND	GND	Black wire
VCC	5V	Red wire

Az-Delivery

Sketch example

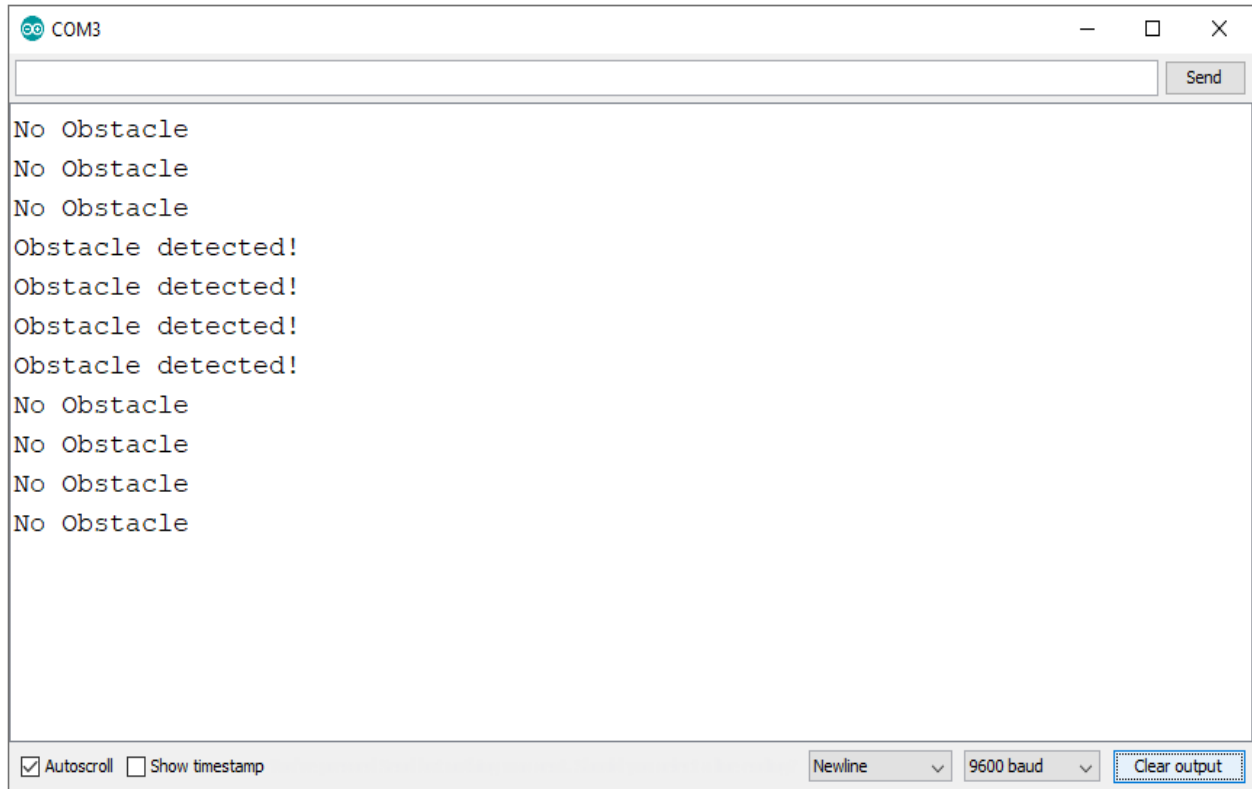
```
#define DIGITAL_PIN 2
boolean sensorOut = HIGH;

void setup() {
  Serial.begin(9600);
  pinMode(DIGITAL_PIN, INPUT);
}

void loop() {
  sensorOut = digitalRead(DIGITAL_PIN);
  if (sensorOut == LOW)
  {
    Serial.println("Obstacle detected!");
  }
  else
  {
    Serial.println("No Obstacle");
  }
  delay(1000);
}
```

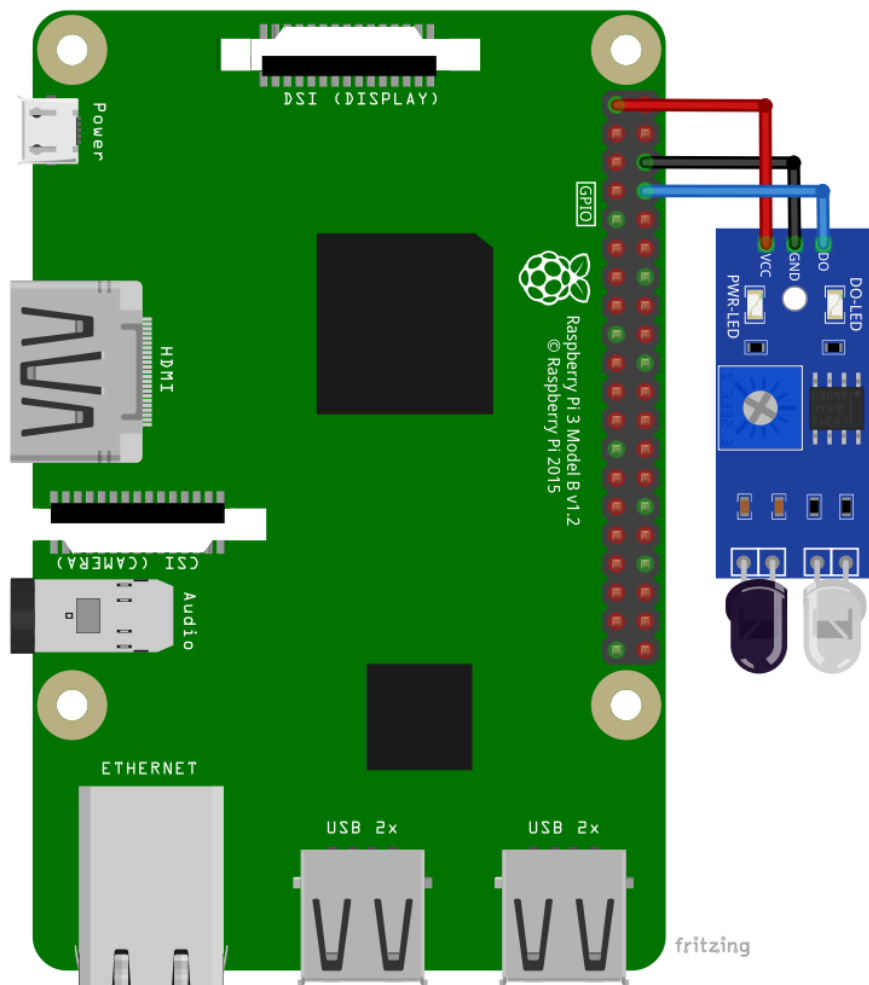
Az-Delivery

Upload the sketch to the Uno and run the Serial Monitor (*Tools > Serial Monitor*). The result should look like as on the following image:



Connecting the module with Raspberry Pi

Connect the module with the Raspberry Pi as shown on the following image:



Module pin	Raspberry Pi pin	Physical pin	Wire color
VCC	3.3V	1	Red wire
GND	GND	6	Black wire
OUT	GPIO14	8	Blue wire



Libraries and tools for Python

To use the module with the Raspberry Pi, the library RPi.GPIO has to be installed. If the library is already installed, running the installation command only updates the library to a newer version.

To install the library, open the terminal and run the following commands, one by one:

```
sudo apt-get update && sudo apt-get upgrade
```

```
sudo apt-get install python3-rpi.gpio
```

Az-Delivery

Python script

```
import time
import RPi.GPIO as GPIO

GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)

DIGITAL_PIN = 14
GPIO.setup(DIGITAL_PIN, GPIO.IN)
time.sleep(2)

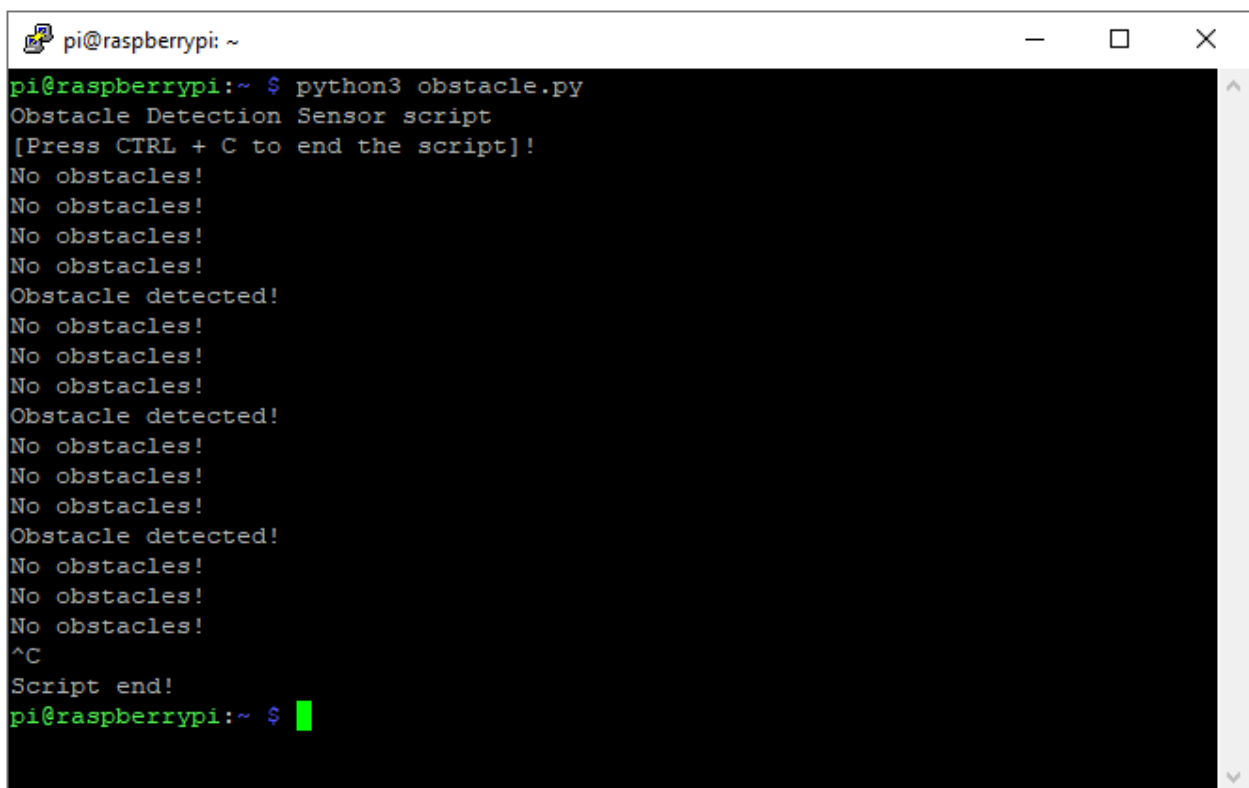
print('Obstacle Detection Sensor script')
print('[Press CTRL + C to end the script]!')
try: # Main program loop
    while True:
        if GPIO.input(DIGITAL_PIN)==0:
            print('Obstacle detected!')
            time.sleep(2)
        else:
            print('No obstacles!')
            time.sleep(2)
except KeyboardInterrupt:
    print('\nScript end!')
finally:
    GPIO.cleanup()
```


Az-Delivery

Save the script by the name *obstacle.py*. To run the script, open the terminal in the directory where the script is saved and run the following command:

```
python3 obstacle.py
```

The result should look like as on the following image:



```
pi@raspberrypi: ~  
pi@raspberrypi:~ $ python3 obstacle.py  
Obstacle Detection Sensor script  
[Press CTRL + C to end the script]!  
No obstacles!  
No obstacles!  
No obstacles!  
No obstacles!  
Obstacle detected!  
No obstacles!  
No obstacles!  
No obstacles!  
Obstacle detected!  
No obstacles!  
No obstacles!  
No obstacles!  
Obstacle detected!  
No obstacles!  
No obstacles!  
No obstacles!  
Obstacle detected!  
No obstacles!  
No obstacles!  
No obstacles!  
^C  
Script end!  
pi@raspberrypi:~ $
```

To stop the script press 'CTRL + C' on the keyboard.

AZ-Delivery

Now it is the time to learn and make your own projects. You can do that with the help of many example scripts and other tutorials, which can be found on the internet.

If you are looking for the high quality products for Arduino and Raspberry Pi, AZ-Delivery Vertriebs GmbH is the right company to get them from. You will be provided with numerous application examples, full installation guides, eBooks, libraries and assistance from our technical experts.

<https://az-delivery.de>

Have Fun!

Impressum

<https://az-delivery.de/pages/about-us>